





PAGER

Version 1

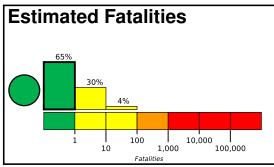
10,000

100,000

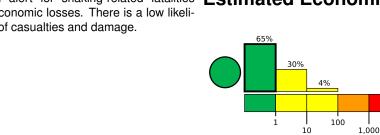
M 5.4, 89 km ENE of Yigo Village, Guam

Origin Time: 2020-11-24 00:00:23 UTC (Tue 10:00:23 local) Location: 13.7561° N 145.6849° E Depth: 46.5 km

Created: 2 hours, 34 minutes after earthquake



Green alert for shaking-related fatalities Estimated Economic Losses and economic losses. There is a low likelihood of casualties and damage.



Estimated Population Exposed to Earthquake Shaking

ESTIMATED POPULATION EXPOSURE (k=x1000)		_*	198k	27k	0	0	0	0	0	0
ESTIMATEI MERCALLI	MODIFIED INTENSITY	I	11-111	IV	V	VI	VII	VIII	IX	X+
PERCEIVE	SHAKING	Not felt	Weak	Light	Moderate	Strong	Very Strong	Severe	Violent	Extreme
POTENTIAL DAMAGE	Resistant Structures	None	None	None	V. Light	Light	Moderate	Mod./Heavy	Heavy	V. Heavy
	Vulnerable Structures	None	None	None	Light	Moderate	Mod./Heavy	Heavy	V. Heavy	V. Heavy

^{*}Estimated exposure only includes population within the map area.

Population Exposure

12.8°N

population per 1 sq. km from Landscan



Structures

Overall, the population in this region resides in structures that are a mix of vulnerable and earthquake resistant construction. The predominant vulnerable building types are informal (metal, timber, GI etc.) and unknown/miscellaneous types construction.

Historical Earthquakes

Date	Dist.	Mag.	Max	Shaking
(UTC)	(km)		MMI(#)	Deaths
2001-10-12	131	7.0	VII(48k)	0
2002-04-26	131	7.0	VIII(2k)	0
1993-08-08	121	7.7	IX(3k)	0

Recent earthquakes in this area have caused secondary hazards such as landslides and liquefaction that might have contributed to losses.

Selected City Exposure

MMI	City	Population
IV	Dededo Village	45k
Ш	Tamuning-Tumon-Harmon	20k
	Village	
Ш	Mongmong-Toto-Maite Village	7k
Ш	Barrigada Village	9k
Ш	Yigo Village	21k
Ш	Mangilao Village	15k
Ш	Chalan Pago-Ordot Village	7k
Ш	Yona Village	6k
Ш	Santa Rita Village	8k
Ш	San Jose Village	15k
Ш	Saipan	48k

bold cities appear on map.

(k = x1000)

PAGER content is automatically generated, and only considers losses due to structural damage. Limitations of input data, shaking estimates, and loss models may add uncertainty.